



#### Revolutionising underwater sensing and sampling technology for ocean observation

Cost-effective marine instrumentation targeting a range of Essential Ocean Variables that can be integrated within existing, low-energy consumption platforms

types of cost-effective sensors & samples

biological & biogeochemical EOVs (Essential Ocean Variables covered





Populations of commercial species





Eutrophication





contaminants













WiSens TD - Chl-a





Silicate Electrochemical





Submersible Sampler for Nanoplastics and Microplastics-SuNaMips



Carbonate Sensors



Phytoplankton Sampler



Downward Looking Sensors



Deep ocean low-level radioactivity sensor



Passive broadband acoustic recording sensor for noise monitoring



Fluorometric Oxygen Sensor



Animal-borne tracking device for ocean data

























































## Objectives

1. Design an OSSE System for the operational model SOMA.

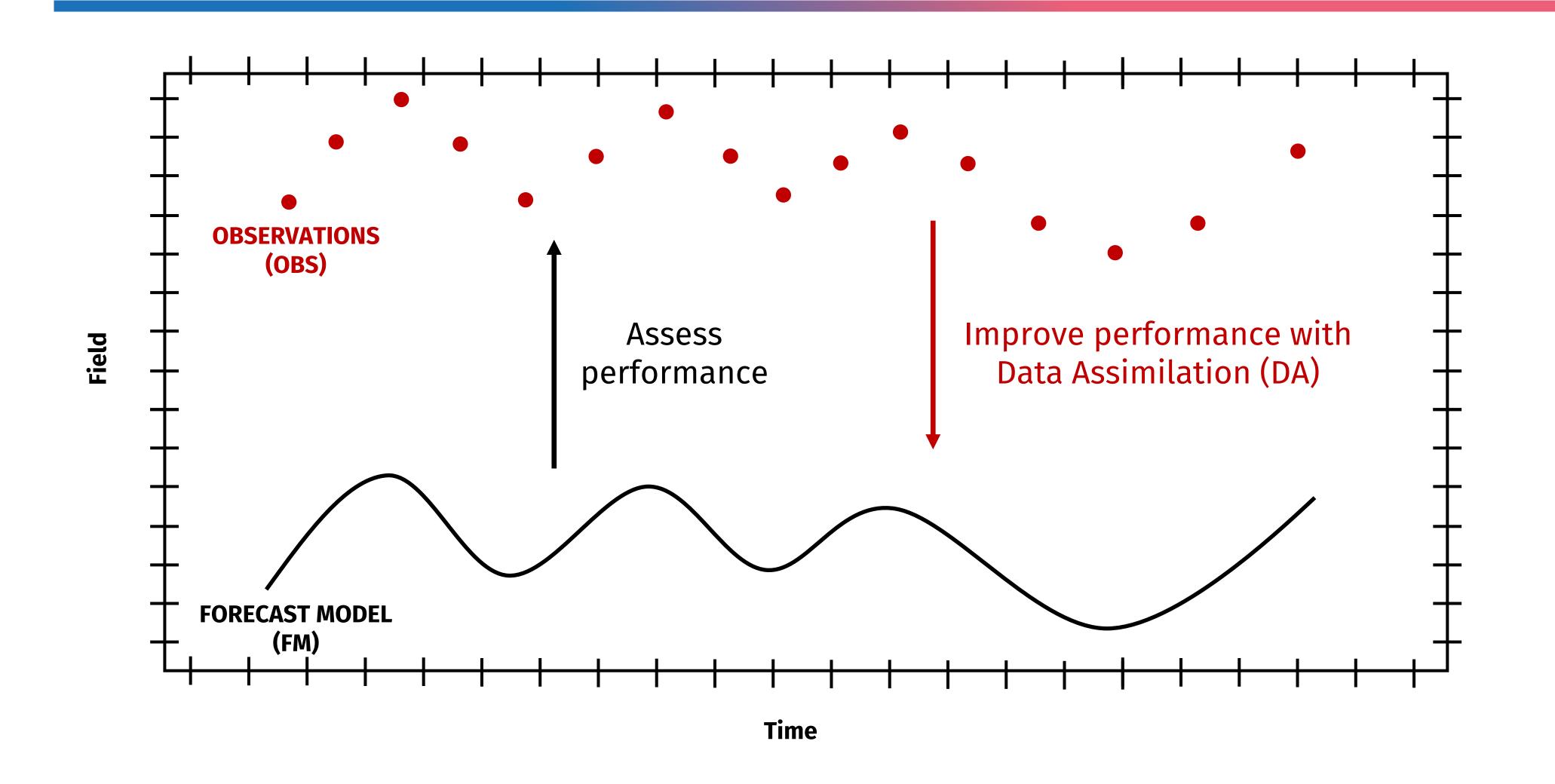


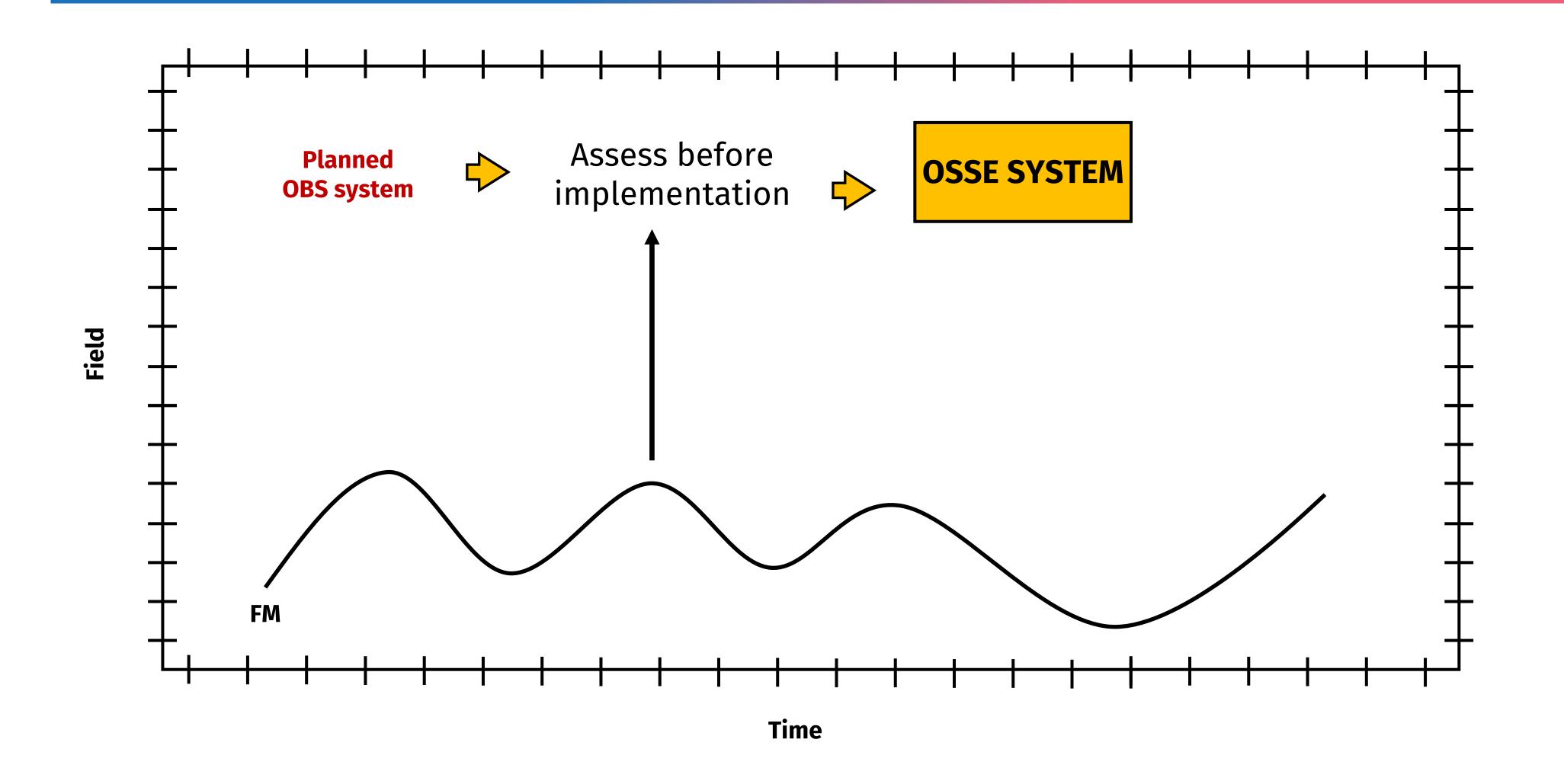
2. Use the OSSE System to test different observation scenarios.

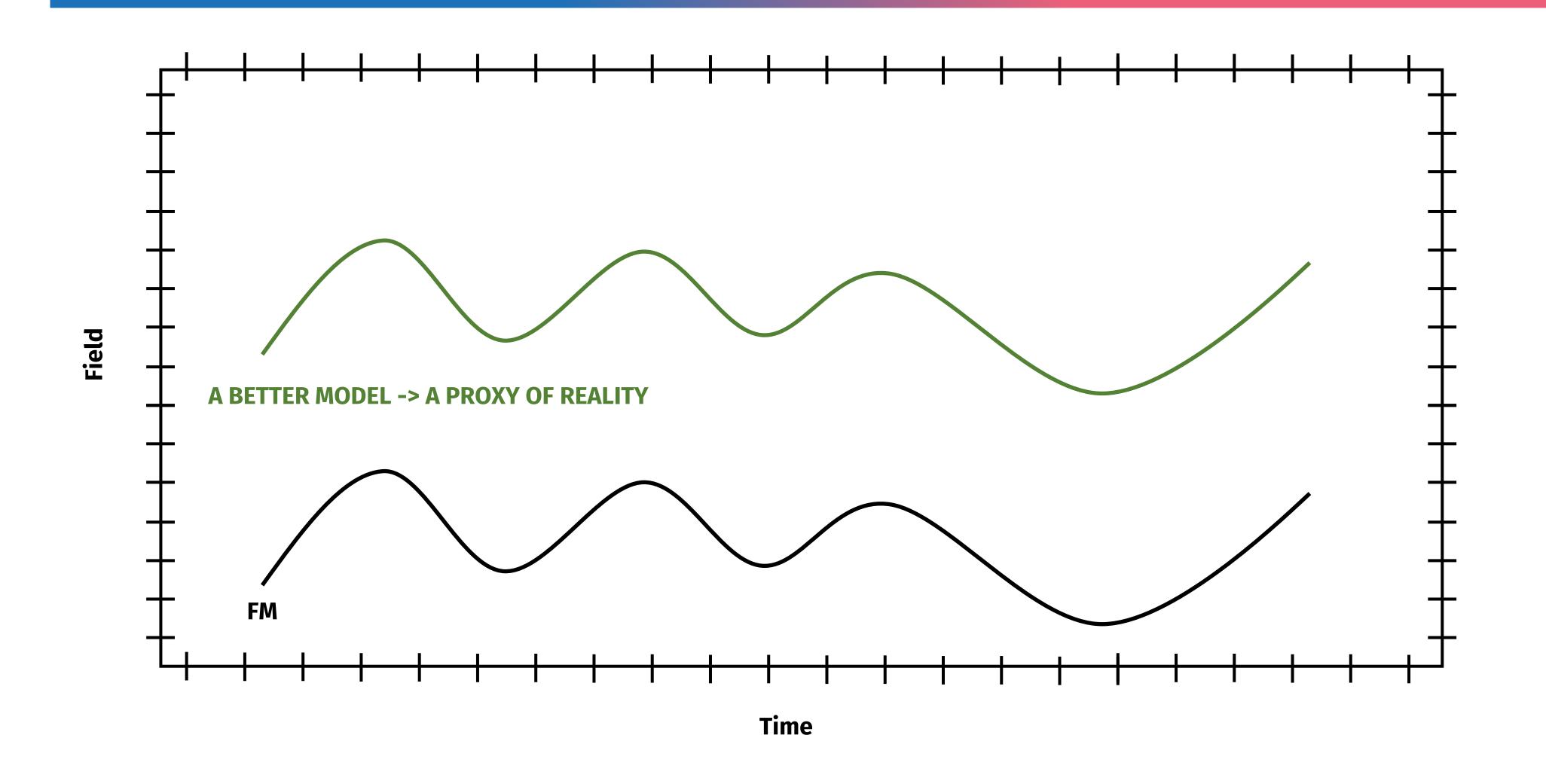


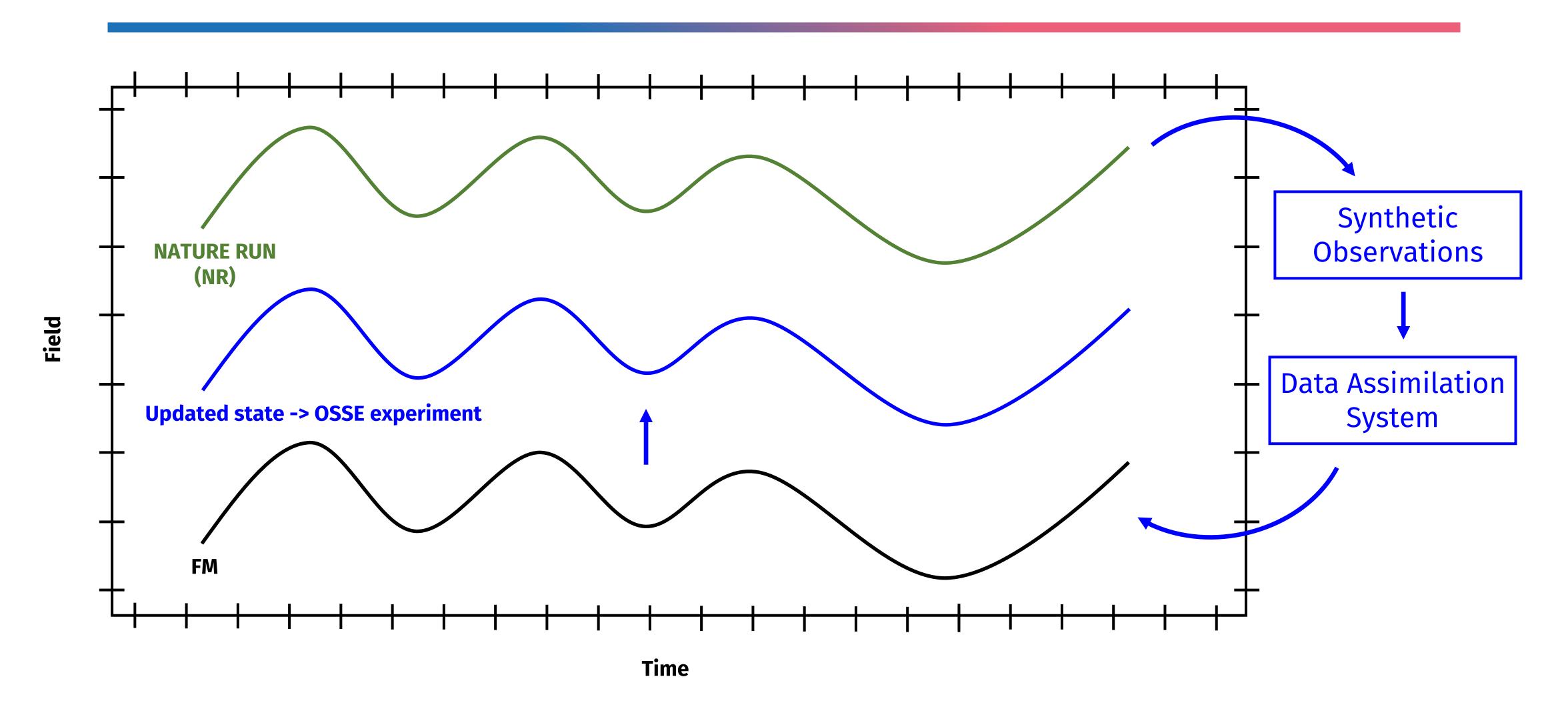
3. Apply the Data Assimilation System used in the OSSE to improve SOMA's forecasting capabilities.











Synthetic Observations

1. Modulate realistic observation errors

2. Compare with a corresponding Observing System Experiment (OSE)

Real observations

#### **OSSE** validation

Avoids overestimating or underestimating the value of proposed observational systems, which leads to biased decisionmaking in sensor deployment.

### Algarve Operational Modelling and Monitoring System (SOMA)

#### **Specifications**

- □MOHID-based
- ☐ Bathymetric data from EMODNET
- ☐ Downscaling domains:
  - 2 km resolution grid in Level 1
  - 1 km resolution grid in Level 2
- □50 cartesian coordinates layers

#### **Boundary forcing**

□Ocean : CMEMS Global solution

Weekly restart

38.0

37.5

37.0

☐Atmosphere : SKIRON

☐Tide : FES2014

1 000 36.5 500 -10.0 -9.5 -9.0 -8.5 -8.0 -7.5 -7.0 1<sub>b</sub> 38.0 2 500 37.5-2 000 1500 37.0-36.5 500 -8.0 -9.0 -8.5 -10.0 -9.5 -7.5

1a

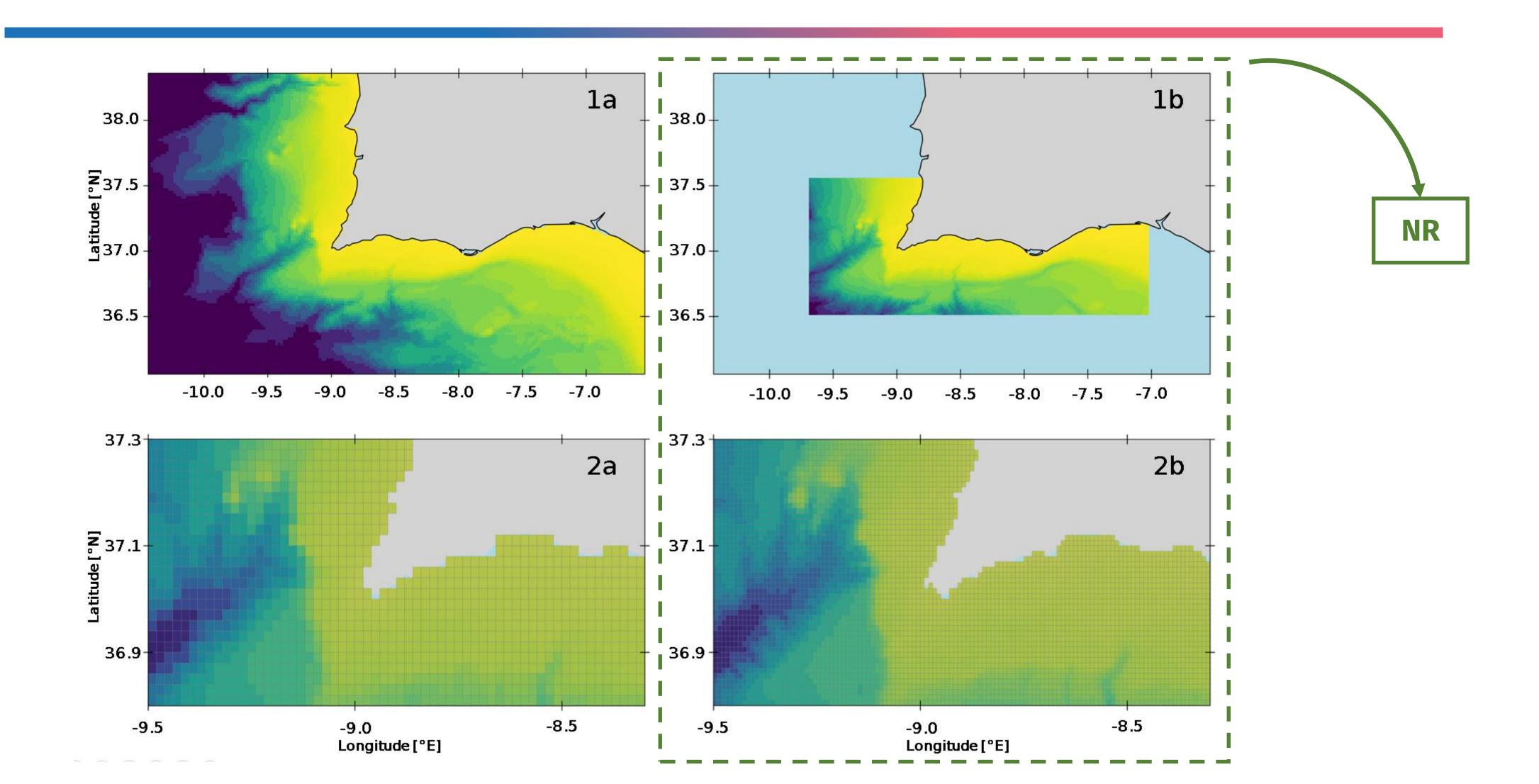
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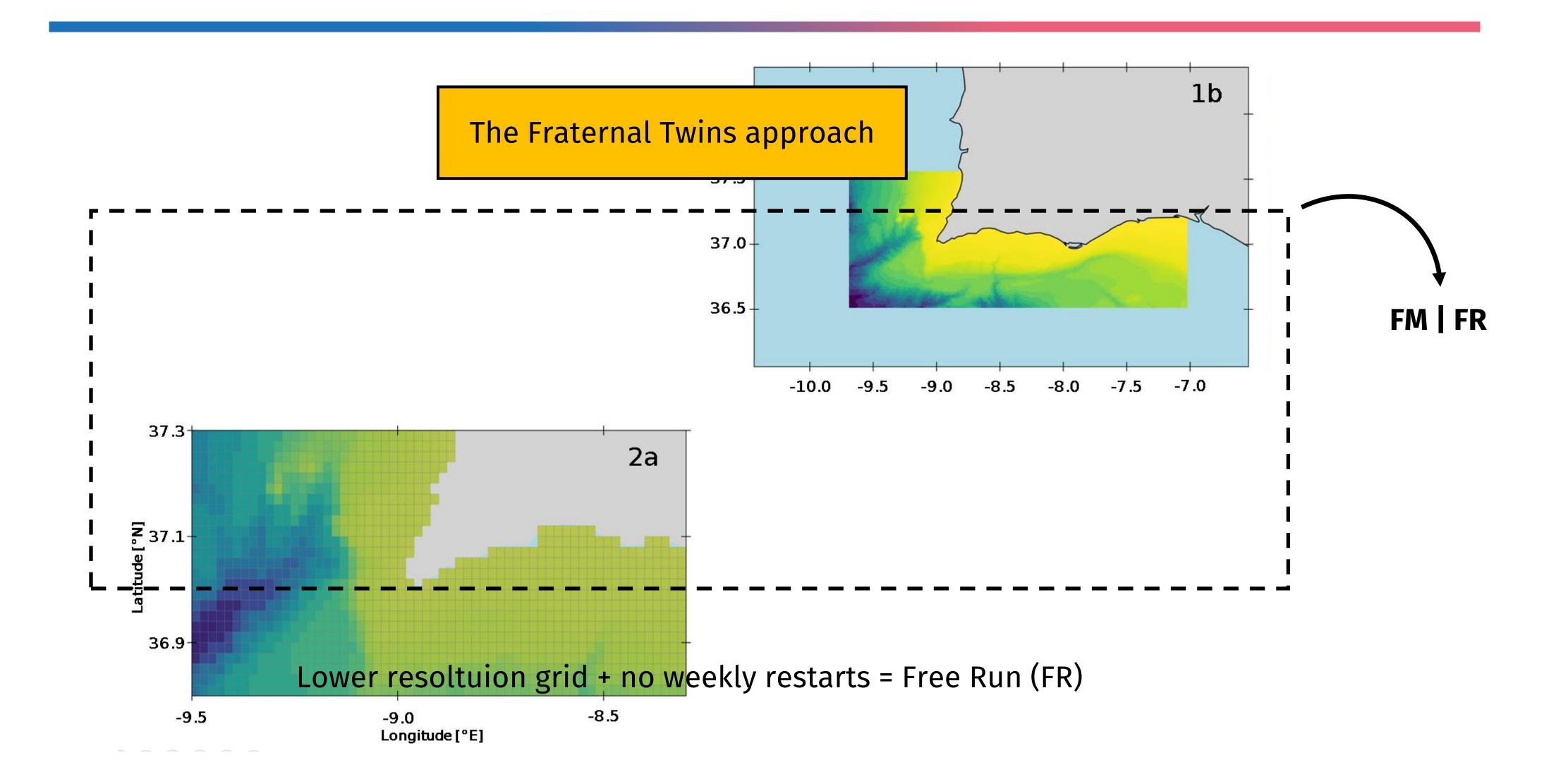
2 5 0 0

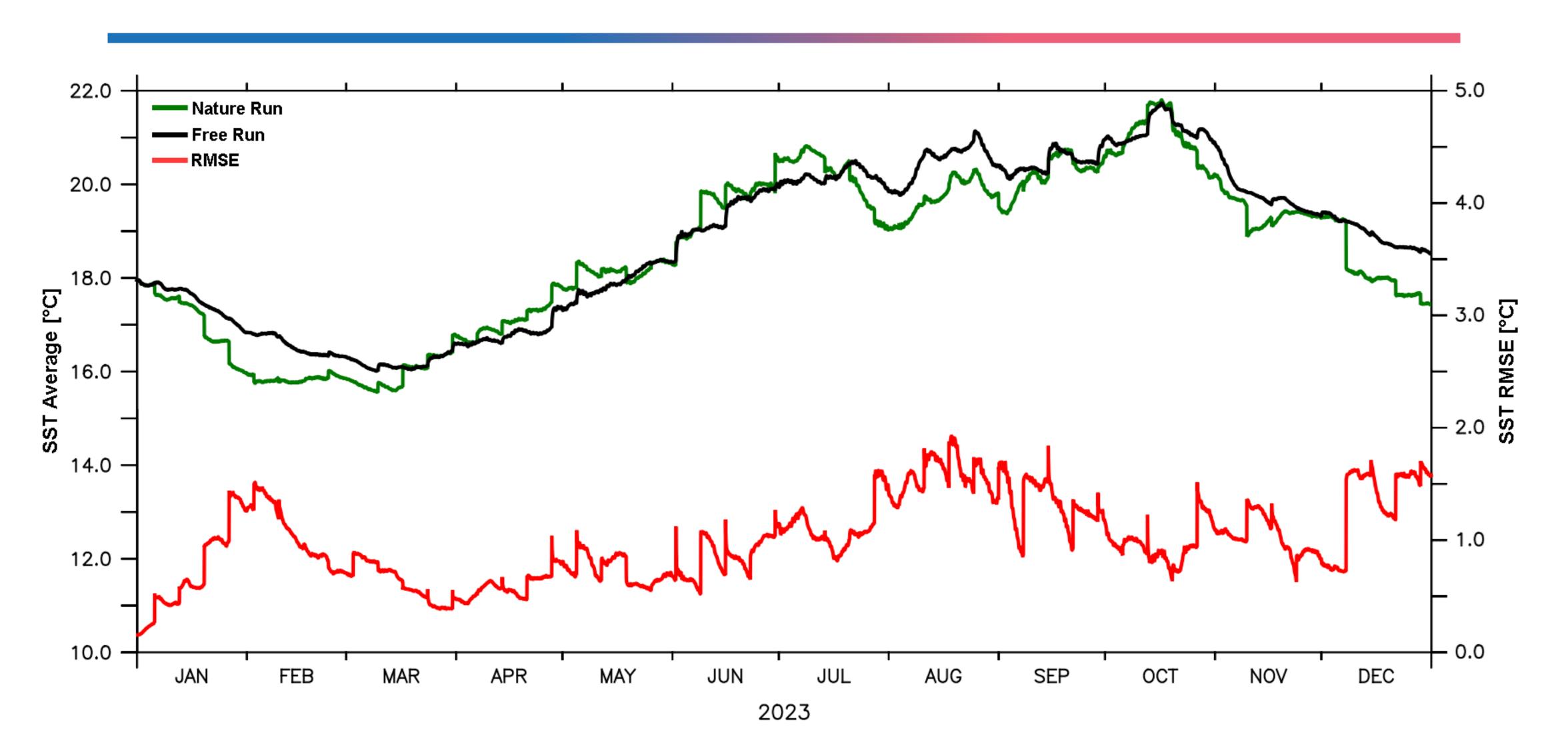
2 000

1500

Forecast access and visualization: <a href="https://soma.ualg.pt">https://soma.ualg.pt</a>







#### Data Assimilation (DA) System

- ☐ Ensemble Optimal Interpolation (EnOI) scheme.
  - Computationally cheap.
  - Time-invariant error statistics: model error is obtained from a fixed ensemble of the model anomalies.



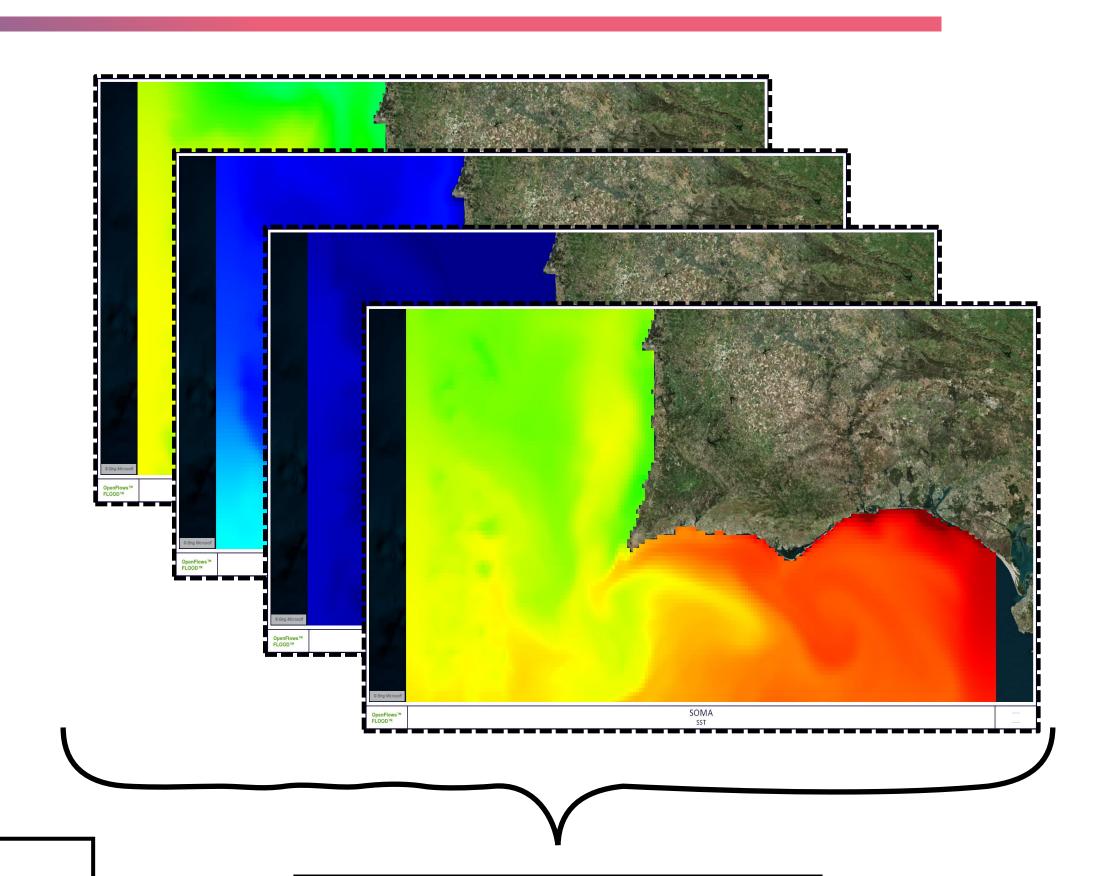
1 model state for every 25h
over a 1-year integration



Catch system variability



354 ensemble members



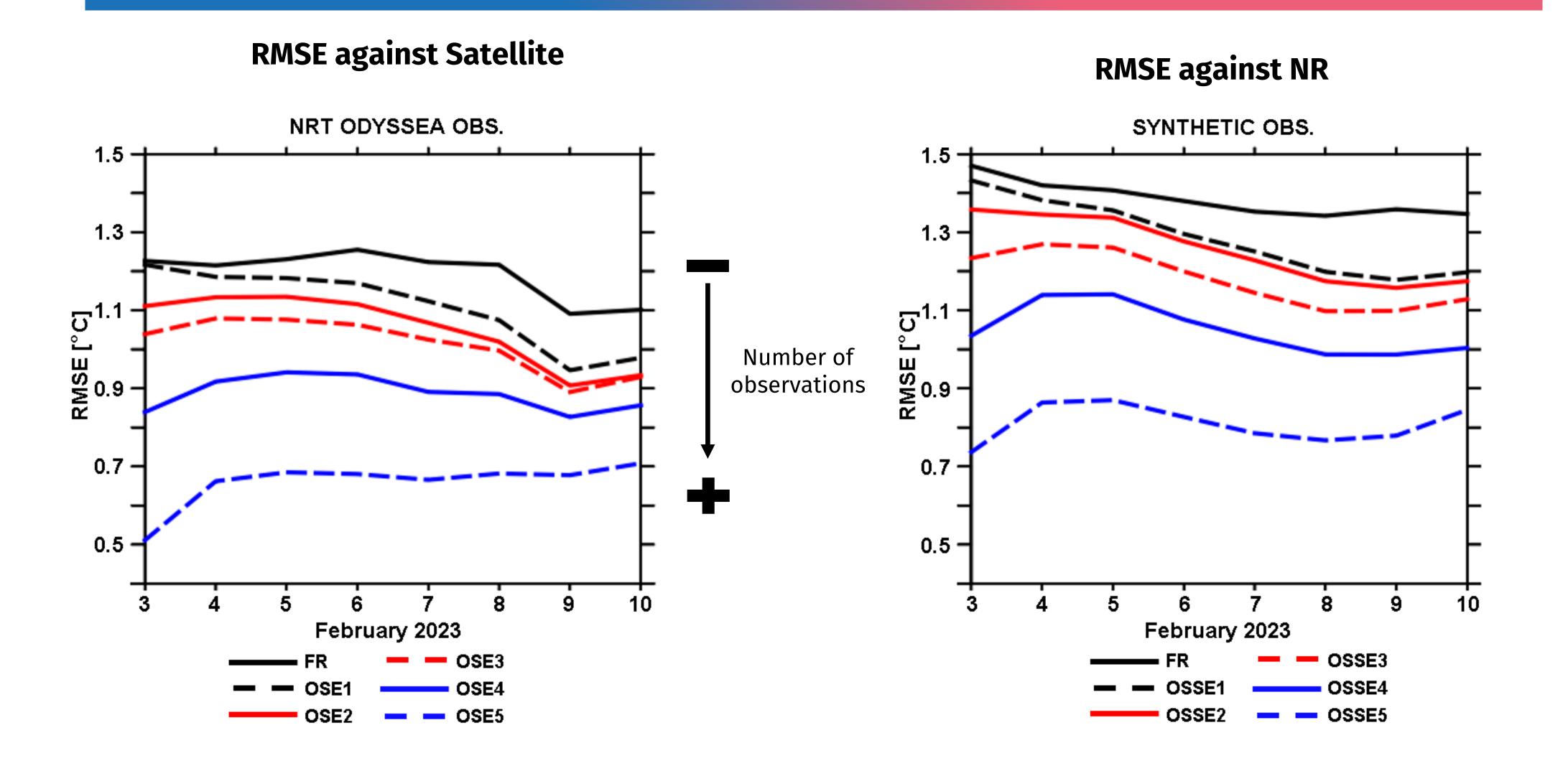
# OSSE Experiments Design

Experiment	ľ	Number of Points	Data Source	Observation Error	
$OSE_1$		10			
$OSE_2$		50	CMEMC NDT		
$OSE_3$		100	ODYSSEA	from data source	
$OSE_4$		200			
$OSE_5$		500			
$OSSE_1$		10		$random\_field$	$\overline{l_1}$
$OSSE_2$		50	CMEMS NRT ODYSSEA	$random\_field_2$	$l_2$
$OSSE_3$		100		$NRT\_ODYSSEA  imes random\_field$	$l_3$
$OSSE_4$		200		$random\_field_4 \\ random\_field_5$	$l_4$
$OSSE_5$		500			$l_5$
	(				
		<b>*</b>			

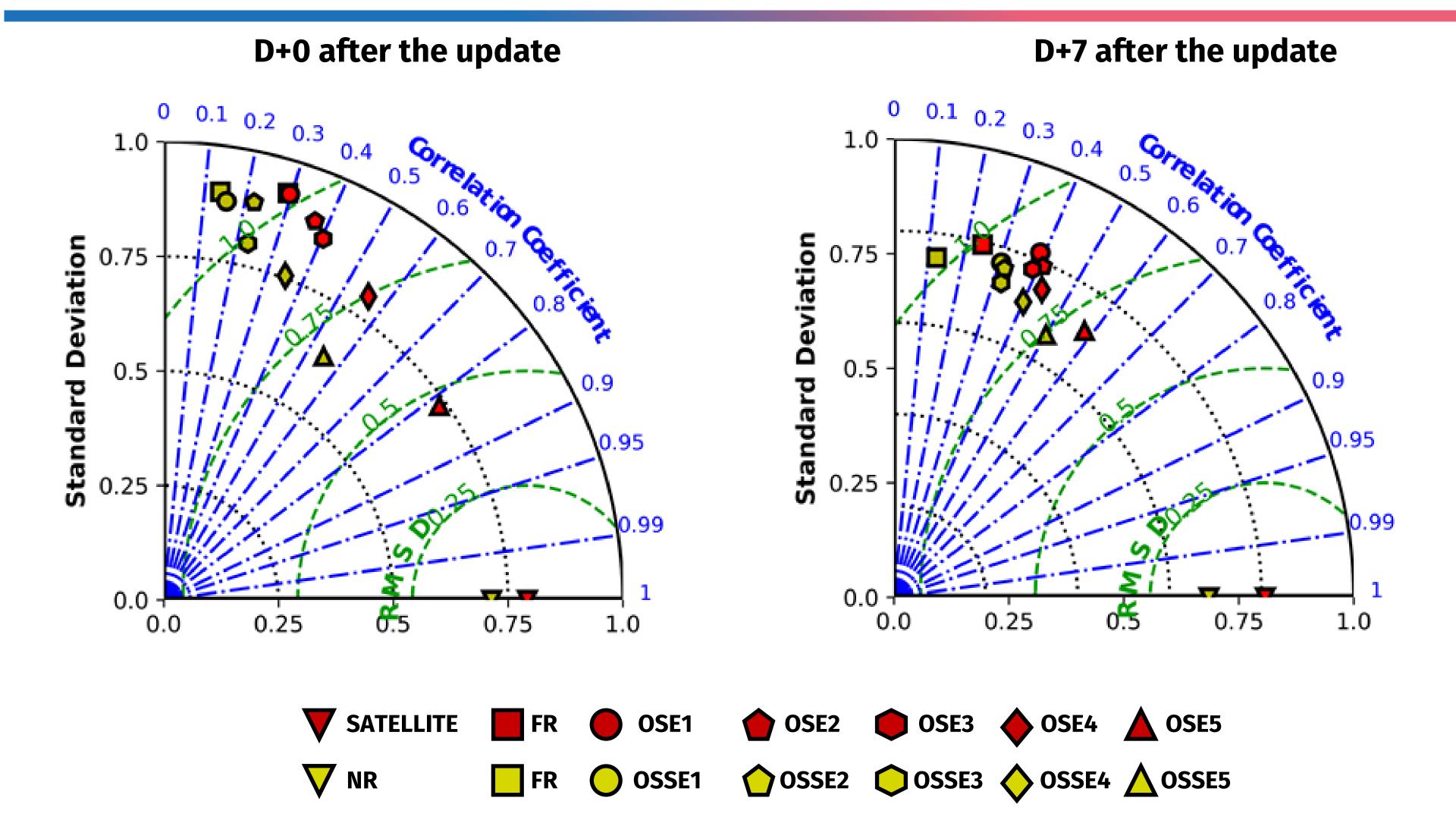
Random points

Modulated error

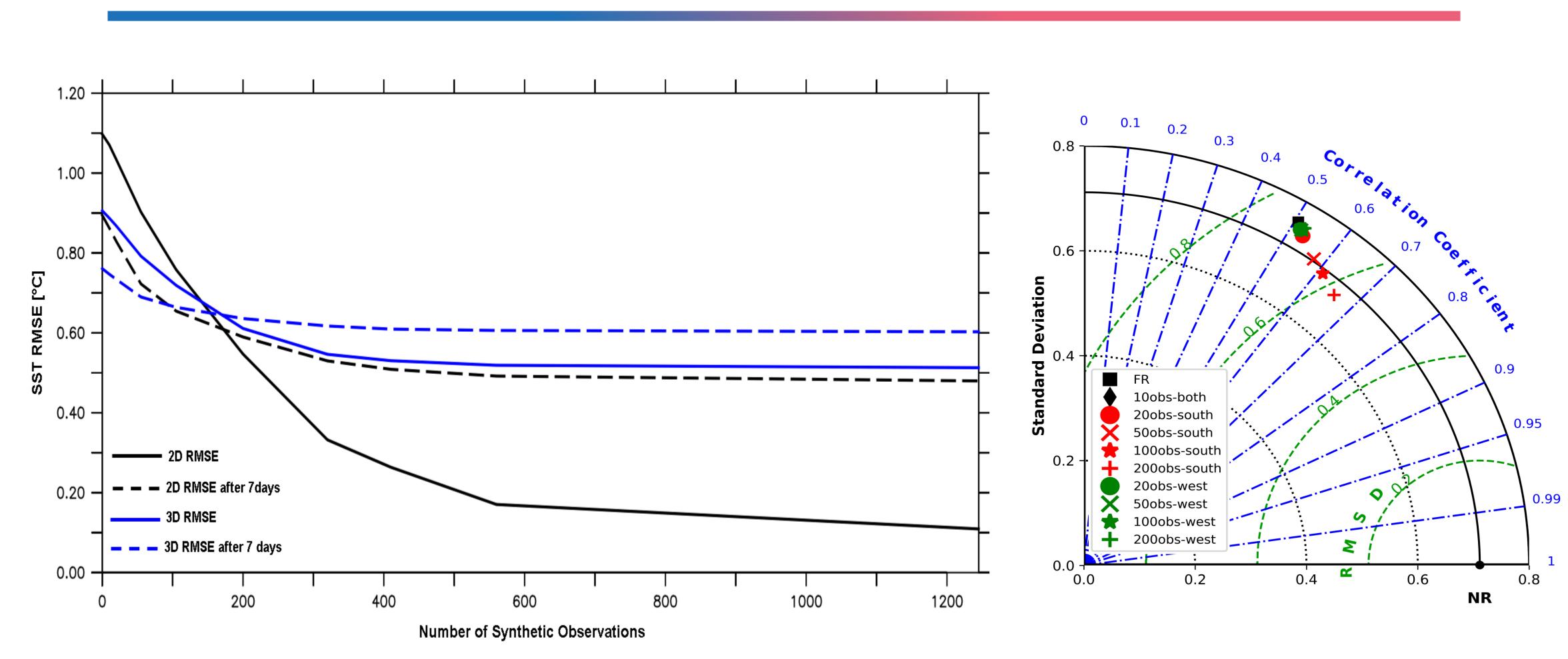
## OSSE System Results



### OSSE System Results



#### Observations Scenarios

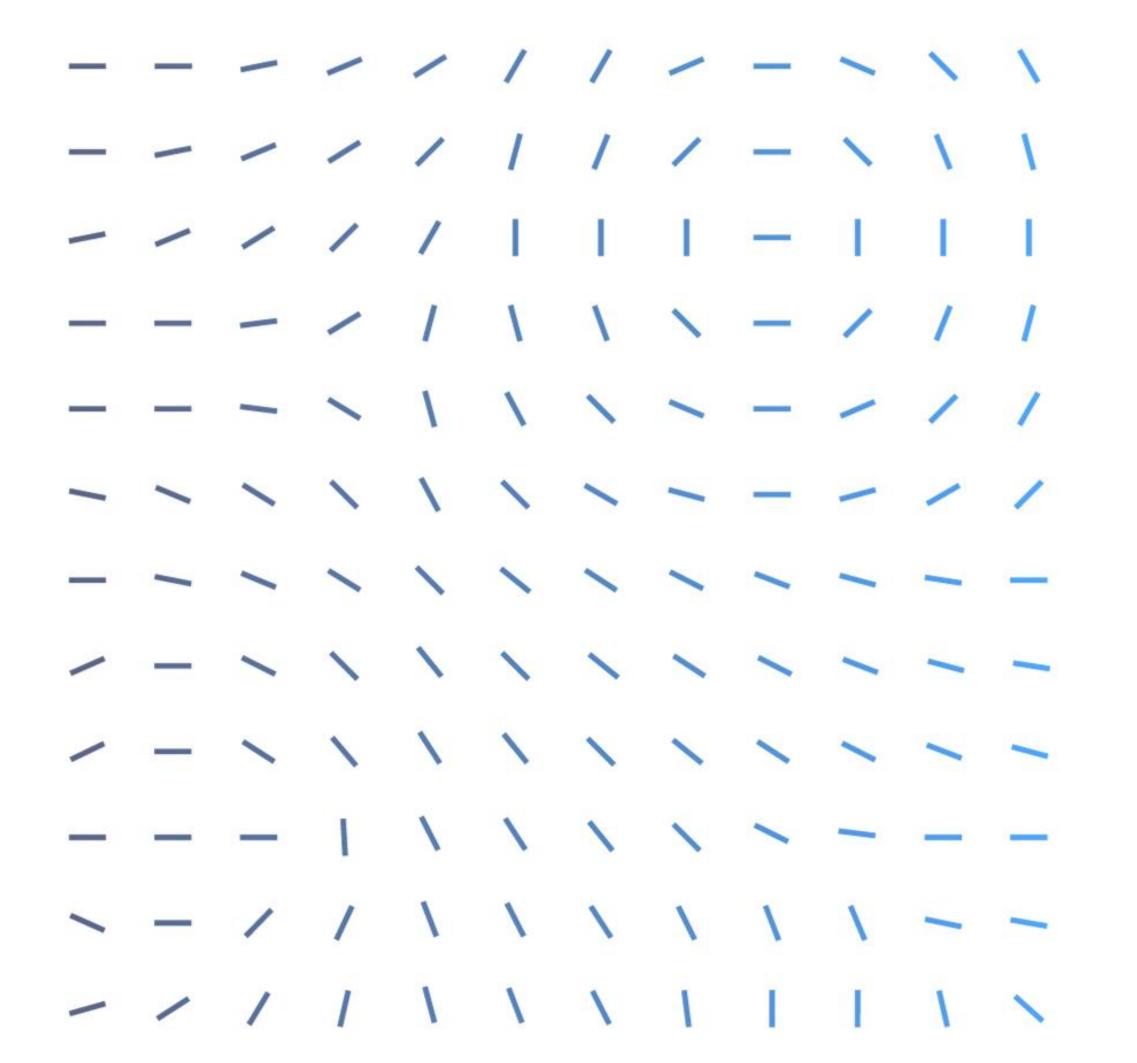


#### Conclusions

- ☐ Similar results when the OSSE system was tested against another data product which provides the same variable (SST).
- ☐ OSSE system is already being used to test different observation scenarios.
- ☐ The development of this work led to the adaptation of a DA system for SOMA, which will later be integrated in its operational forecast.







#### Thank you!

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MOHIDing 2025







